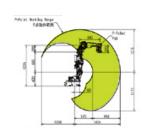
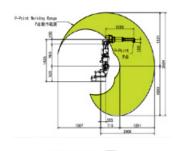
## 7-AXIS ULTRA-FLEX WELDING ROBOT

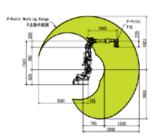


1 D-11D-13	
Reach	1435mm
Payload	4 Kg
Axes	7
Repeatability	±0.08mm



### FD-NV6LS

Reach	2006mm
Payload	6 Kg
Axes	7
Repeatability	±0.08mm
	•



### FD-NB4LS

FD-NV6S

Payload

Axes

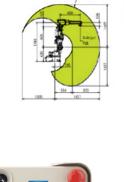
Reach	2008mm
Payload	4 Kg
Axes	7
Repeatability	±0.08mm



ALES CONTRACTOR OF THE PROPERTY OF THE PROPERT	FD-NV203
SI CE	Reach
	Payload
	Axes
	Repeatabil
180	

### FD-NV20S

Reach	1710mm
Payload	20 Kg
Axes	7
Repeatability	±0.08mm



1427mm

6 Kg

7 Repeatability ±0.08mm

**FD TEACHING PENDANT** Small And Light The FD Teaching Pendant is 27% lighter and 40% smaller than our previous model, making tight spaces a non-issue and teaching sessions easier.



With this feature, you can now back up all data directly from the teaching pendant. A USB memory slot makes backing up data quick and easy.



### **FD11 Robot Controller**

- Windows XP based open architecture
- Large memory capacity and 40 Input / 40 Output control signals
- Advanced PLC functions allow for ladder diagram editing directly through the teaching pendant
- Network capabilities connects to Ethernet. DeviceNet, and PROFIBUS connections (may require additional hardware)

# 7-AXIS ULTRA-FLEX **WELDING ROBOT**



888-0TC-R0B0

www.daihen-usa.com

**AVOIDS** INTERFERENCE **HIGH-DENSITY INSTALLATION** 

**OPTIMUM TEACHING** 

**SPACE & COST SAVING**  **BUILT-IN CABLES** 

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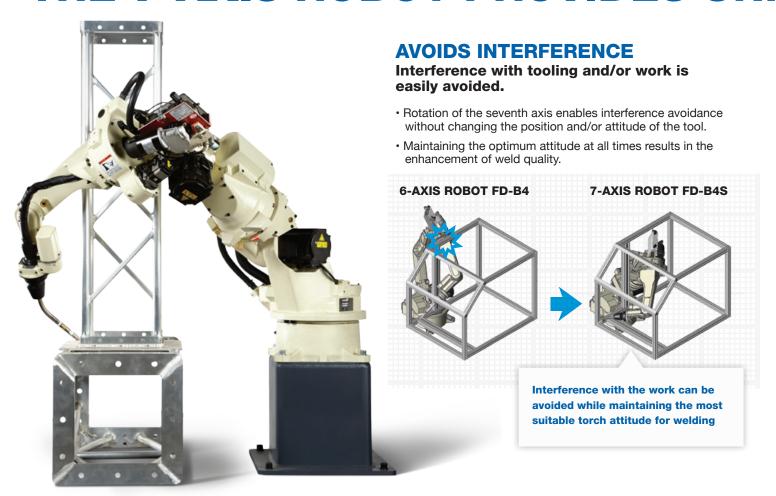


DAIHEN INC.

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# THE 7-AXIS ROBOT PROVIDES UNMATCHED FREEDOM OF MOVEMENT



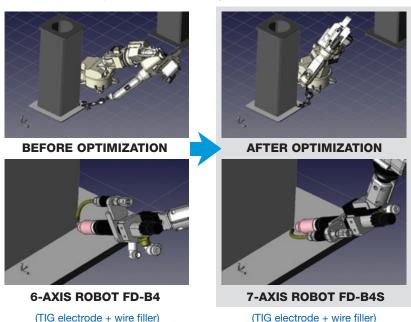
### **OPTIMUM TEACHING**

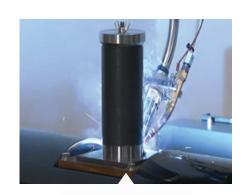
Easy teaching, even for a two-electrode torch.

Teaching a welding line only to the leading torch automatically corrects the position and attitude of the robot so the following torch will also follow the same welding line.

Changing the torch attitude without changing the arm attitude provides freedom from interference even after the automatic correction.

Example of optimum attitude teaching with a two-electrode torch



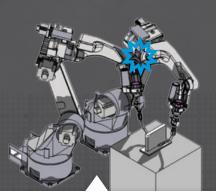


(Cold Tandem GMAW)

### **HIGH-DENSITY INSTALLATION**

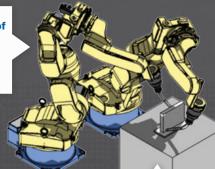
Multiple 7-axis robots create a compact production line.

Thanks to **flexible attitude changes** by using the seventh axis, robots can easily move around obstructions. Placing multiple robots in close proximity allows for efficient integration and can shorten the manufacturing process.



 One arm interferes with another, making it necessary to separate the welding process, which increases the tack time.

The motion of the seventh axis avoids interference



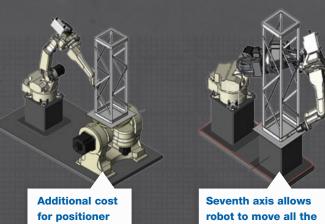
- Interference between arms can be avoided. while maintaining the most suitable torch attitude for welding.
- Welding process need not be separated, which shortens the tack time.

### **SPACE & COST SAVING**

The seventh axis may eliminate the need for additional positioners.

Rotation of the seventh axis enables a flexible attitude change when moving around obstructions.

Access to a proper welding position is possible without using a positioner, reducing installation area and costs compared with a conventional 6-axis system.



6-AXIS ROBOT FD-B4

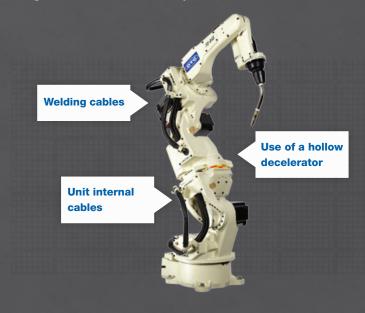
way around

**7-AXIS ROBOT FD-B4S** 

## **BUILT-IN CABLES**

Weld cables are housed in the J7-axis to avoid interference.

Both internal robot cables and **weld cables are built into the J7-axis**, making it possible to **use the movable full range** without interference affecting peripheral devices due to the irregular movement of externally wired cables.



7-AXIS ROBOT FD-B4S 6-AXIS ROBOT FD-B4